

So we have two classes: **explicit methods**, and **implicit methods**.  
In all cases we want the sequence  $\{y_0, y_1, \dots, y_N\}$  to converge to the sequence  $\{y_0, y(t_1), \dots, y(T)\}$ .

If, given a method, we can prove that

$$\exists C > 0 \text{ such that } \max_n |y_n - y(t_n)| \leq C \Delta t^p$$

with  $C$  independent of  $\Delta t$  and  $p > 0$ , then we say that *the method is convergent*, and *the order of convergence is  $p$*  (the bigger  $p$ , the faster the convergence).

### Theorem 1 (Lax)

*If a scheme is **consistent** and **stable**, then it is convergent, and the order of convergence is the order of consistency.*

We have however yet to define what *consistency* and *stability* are....

## Intuitive explanation of *consistency* and *stability*

- the *consistency error* at a given time step measures the error which is created at that step; it is defined as *the error made when the scheme is applied to the exact solution of the problem*. It can be seen that the consistency error measures of how much the discrete scheme resembles the differential problem.
- *stability* measures how the error, created and accumulated during the previous steps, goes to the next step (is it amplified? does it decay?...)

## Consistency of a scheme

**Consistency** is a measure of how much the discrete scheme resembles the differential problem: the *consistency error* is *the error made when the scheme is applied to the exact solution of the problem*.

The *consistency error* of a given scheme is defined as

$$\tau = \max_{n=1, \dots, N} |\tau_n|$$

where  $\tau_n$  is the *local truncation error* at the step  $n$ , that is defined as:

$$\tau_n = \frac{y(t_{n+1}) - \tilde{y}_{n+1}}{\Delta t}$$

where  $\tilde{y}_{n+1}$  is obtained applying one step of the method to the exact solution at the previous time instant  $y(t_n)$ . We say that the scheme is consistent of order  $p$  if:

$$\exists C > 0, \text{ independent of } \Delta t, \text{ s. t. } \tau \leq C \Delta t^p$$

We observe that if the numerical scheme is consistent, then  $\tau \rightarrow 0$  for  $\Delta t \rightarrow 0$ .

## Consistency of Explicit Euler

The exact solution fulfils:  $y'(t_n) - f(t_n, y(t_n)) = 0$ ,  $n = 0, 1, 2, \dots$

If we apply the Explicit Euler scheme to the exact solution we will have:

$$\tilde{y}_{n+1} = y(t_n) + \Delta t f(t_n, y(t_n))$$

Since  $y'(t_n) = f(t_n, y(t_n))$ , by Taylor expansion centered in  $t_n$ , there exists  $z \in [t_n, t_{n+1}]$  such that

$$y(t_{n+1}) = y(t_n) + \Delta t y'(t_n) + \frac{\Delta t^2}{2} y''(z) = y(t_n) + \Delta t f(t_n, y(t_n)) + \frac{\Delta t^2}{2} y''(z)$$

Thus, the local truncation error becomes

$$\tau_n = \frac{y(t_{n+1}) - \tilde{y}_{n+1}}{\Delta t} = \frac{y(t_{n+1}) - y(t_n)}{\Delta t} - f(t_n, y(t_n)) = \frac{\Delta t}{2} y''(z),$$

and the consistency error is then

$$\tau = \max |\tau_n| \leq \frac{\Delta t}{2} \max_{t \in [t_0, T]} |y''(t)| = C \Delta t.$$

Thus, Explicit Euler scheme is consistent with **order of consistency 1**.

## Consistency of the Heun method

We apply the Heun scheme again to the exact solution  $\tilde{y}_n = y(t_n)$ :

$$\tilde{y}_{n+1} = y(t_n) + \frac{\Delta t}{2} (f(t_n, y(t_n)) + f(t_{n+1}, y(t_n) + \Delta t f(t_n, y(t_n))))$$

Since  $f(t_n, y(t_n)) = y'(t_n)$ , by Taylor expansion centered in  $t_n$ , there exists  $z_1 \in [t_n, t_{n+1}]$  such that

$$\begin{aligned} y(t_{n+1}) &= y(t_n) + (t_{n+1} - t_n) y'(t_n) + \frac{\Delta t^2}{2} y''(z_1) \\ &= y(t_n) + \Delta t y'(t_n) + \frac{\Delta t^2}{2} y''(z_1) \end{aligned} \tag{1}$$

and, by Taylor expansion centered in  $t_{n+1}$ , there exists  $z_2 \in [t_n, t_{n+1}]$  such that

$$\begin{aligned} y(t_n) &= y(t_{n+1}) + (t_n - t_{n+1}) y'(t_{n+1}) + \frac{\Delta t^2}{2} y''(z_2) \\ &= y(t_{n+1}) - \Delta t y'(t_{n+1}) + \frac{\Delta t^2}{2} y''(z_2) \end{aligned} \tag{2}$$

The local truncation error, setting  $\hat{y}_{n+1} = y(t_n) + \Delta t f(t_n, y(t_n))$  and using again that  $y'(t_{n+1}) = f(t_{n+1}, y(t_{n+1}))$  is:

$$\begin{aligned}
 \tau_n &= \frac{y(t_{n+1}) - \tilde{y}_{n+1}}{\Delta t} \\
 &= \frac{(y(t_{n+1}) - y(t_n) - \frac{\Delta t}{2}y'(t_n) - \frac{\Delta t}{2}f(t_{n+1}, \hat{y}_{n+1})))}{\Delta t} \\
 &= \frac{(y(t_{n+1}) - y(t_n) - \frac{\Delta t}{2}y'(t_n) - \frac{\Delta t}{2}y'(t_{n+1}) + \frac{\Delta t}{2}f(t_{n+1}, y(t_{n+1})) - \frac{\Delta t}{2}f(t_{n+1}, \hat{y}_{n+1})))}{\Delta t} \\
 &= \frac{(y(t_{n+1}) - y(t_n) - \frac{\Delta t}{2}y'(t_n) - \frac{\Delta t}{2}y'(t_{n+1}))}{\Delta t} + \frac{1}{2}(f(t_{n+1}, y(t_{n+1})) - f(t_{n+1}, \hat{y}_{n+1})) \\
 &= A + B,
 \end{aligned}$$

where

$$A = \frac{(y(t_{n+1}) - y(t_n) - \frac{\Delta t}{2}y'(t_n) - \frac{\Delta t}{2}y'(t_{n+1}))}{\Delta t}$$

and

$$B = \frac{1}{2}(f(t_{n+1}, y(t_{n+1})) - f(t_{n+1}, \hat{y}_{n+1}))$$

For the first term we have

$$\begin{aligned} A &= \frac{1}{2} \left( \frac{y(t_{n+1}) - y(t_n)}{\Delta t} - y'(t_n) \right) + \frac{1}{2} \left( \frac{y(t_{n+1}) - y(t_n)}{\Delta t} - y'(t_{n+1}) \right) \\ &= \frac{1}{2} \left( \frac{\Delta t}{2} y''(z_1) \right) + \frac{1}{2} \left( -\frac{\Delta t}{2} y''(z_2) \right) = \frac{1}{4} \Delta t (z_1 - z_2) \frac{y''(z_1) - y''(z_2)}{z_1 - z_2} \end{aligned}$$

where we have used the (1) for the first parenthesis and (2) for the second ones. We then apply the Mean Value Theorem to  $y''$ , which states that there exists  $z_3$  between  $z_1$  and  $z_2$  such that:  $\frac{y''(z_1) - y''(z_2)}{z_1 - z_2} = y'''(z_3)$ , and get:

$$|A| = \left| \frac{1}{4} \Delta t (z_1 - z_2) y'''(z_3) \right| \leq \frac{\Delta t^2}{4} |y'''(z_3)|$$

For the second term we have

$$\begin{aligned} |B| &= \frac{1}{2} |f(t_{n+1}, y(t_{n+1})) - f(t_{n+1}, \hat{y}_{n+1})| \\ &\leq \frac{L}{2} |y(t_{n+1}) - \hat{y}_{n+1}| \\ &\leq \frac{L}{2} \frac{\Delta t^2}{2} |y''(z_1)| \end{aligned}$$

where we have assumed and used the Lipschitzianity of  $f$  with respect to its second argument, that is,  $|f(t, \eta_1) - f(t, \eta_2)| \leq L|\eta_1 - \eta_2|$ , and then (1) again. In conclusion

$$\tau = \max |\tau_n| \leq (1 + L) \frac{\Delta t^2}{4} \max_{t \in [t_0, T]} |y'''(t)| = C \Delta t^2$$

Thus, Crank-Nicolson scheme is consistent with [order of consistency 2](#).



## A closer look at consistency error

We found that:

- for the explicit Euler methods, the consistency error is zero whenever  $y'' \equiv 0$ , that is, whenever the solution of the Cauchy Problem is a polynomial of degree up to 1.
- the consistency error for Heun method is zero whenever  $y''' \equiv 0$ , that is, whenever the solution of the Cauchy Problem is a polynomial of degree up to 2.

This suggests that *to have order of consistency  $p$*  means that *the scheme computes exactly the solution of the Cauchy Problem whenever this solution is a polynomial of degree up to  $p$ .*

This is true in general (no proof provided in this course) and is indeed another easier way of checking consistency of a scheme.

## Consistency of implicit methods: implicit Euler

$$\frac{y_{n+1} - y_n}{\Delta t} - f(t_n, y_n) = 0 \quad \forall n$$

Applying this scheme to the exact solution of the Cauchy Problem means considering

$$\tau_n = \frac{y(t_{n+1}) - y(t_n)}{\Delta t} - y'(t_n)$$

which is in general  $\neq 0$ . Is the order of consistency 1? For this we should have the above  $= 0$  when the solution of the Cauchy Problem is  $1, t, t^2$ .

$$\text{When } y(t) = 1, y' = 0 = f, \implies \frac{1 - 1}{\Delta t} - 0 = 0;$$

$$\text{When } y(t) = t, y' = 1 = f, \implies \frac{t_{n+1} - t_n}{\Delta t} - 1 = 1 - 1 = 0;$$

Hence, **the order of consistency of IE method is 1**. Note that

$$\text{When } y(t) = t^2, y' = 2t = f, \implies \frac{t_{n+1}^2 - t_n^2}{\Delta t} - 2t_n = t_{n+1} - t_n \neq 0$$

## Consistency of implicit methods: Crank-Nicolson

$$\frac{y_{n+1} - y_n}{\Delta t} - \frac{1}{2} \left( f(t_n, y_n) + f(t_{n+1}, y_{n+1}) \right) = 0 \quad \forall n$$

Applying this scheme to the exact solution means considering

$$\frac{y(t_{n+1}) - y(t_n)}{\Delta t} - \frac{1}{2} \left( y'(t_n) + y'(t_{n+1}) \right).$$

Let's check the above expression when the solution of the Cauchy Problem is  $1, t, t^2$ :

$$\text{When } y(t) = 1, y' = 0 = f, \implies \frac{1 - 1}{\Delta t} - \frac{1}{2}(0 + 0) = 0;$$

$$\text{When } y(t) = t, y' = 1 = f, \implies \frac{t_{n+1} - t_n}{\Delta t} - \frac{1}{2}(1 + 1) = 1 - 1 = 0;$$

$$\text{When } y(t) = t^2, y' = 2t = f, \implies \frac{t_{n+1}^2 - t_n^2}{\Delta t} - \frac{1}{2}(2t_n + 2t_{n+1}) = 0$$

Hence, the order of consistency of Crank-Nicolson is 2.

# Absolute Stability

The concept of *stability* is another very important and useful concept whose precise definition has to be made precise at various occurrences. Roughly speaking, stability is what guarantees that the errors generated during a numerical procedure do not grow too much.

With Ode stability is a delicate issue, especially when the phenomenon under study has to be followed for a long time. To better see what happens, let us consider a simple model problem, for which we know the exact solution:

$$\begin{cases} y'(t) = ay(t) & t > 0 & a \in \mathbb{C} \\ y(0) = y_0 \end{cases}$$

which exact solution is

$$y(t) = y_0 e^{(\operatorname{Re} a)t} (\cos((\operatorname{Im} a)t) + i \sin((\operatorname{Im} a)t))$$

If  $\operatorname{Re}(a) > 0$  the exact solution *grows* exponentially. We cannot expect (and we do not want!) that the discrete scheme remains bounded, and it is not even the case to discuss “stability”.

Instead, if  $\operatorname{Re}(a) < 0$  the exact solution not only is bounded, but *decays* exponentially:

$$a < 0 \longrightarrow |y(t)| \leq |y_0| \quad \text{and} \quad \lim_{t \rightarrow \infty} |y(t)| = 0.$$

In this case we need to analyse the discrete schemes, and see whether the discrete solution decays too, and behaves like the exact solution. Hence, let  $\operatorname{Re}(a) < 0$ , and let  $\{y_n\}$  be the sequence generated by a numerical scheme. Does  $\{y_n\}$  satisfy the following relation?

$$a \in \mathbb{C} \text{ with } \operatorname{Re} a < 0 \longrightarrow |y_n| \leq |y_0| \quad \text{and} \quad \lim_{n \rightarrow \infty} |y_n| = 0?$$

If this happens, the scheme is called *Absolutely stable*, or *A-stable*.

## Checking A-stability for Explicit Euler

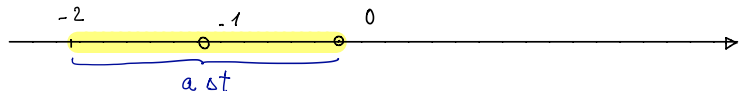
By applying **Explicit Euler** method to the model problem, we get  
( $y_{n+1} = y_n + \Delta t f(t_n, y_n)$  with  $f(t_n, y_n) = ay_n$ )

$$y_{n+1} = (1 + a\Delta t)y_n \quad n = 0, 1, \dots \implies y_n = y_0(1 + a\Delta t)^{n+1}.$$

The exact solution decays exponentially from the initial value  $y_0$ , while the growth-decay factor for the discrete scheme is  $G = 1 + a\Delta t$ .

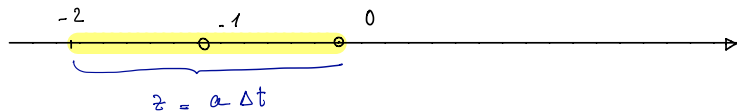
For having  $\lim_{n \rightarrow \infty} |y_n| = 0$  we need  $|G| < 1$ . We observe that  $|1 + a\Delta t|$  is the distance between  $-1$  and  $a\Delta t$ , so  $|G| < 1$  if and only if  $a\Delta t$  is contained in the unit circle centered in  $-1$ .

## Stability for Explicit Euler: the real setting



$$\begin{aligned} \text{EE is stable} &\iff |1 + a \Delta t| < 1 \\ &\iff -2 < a \Delta t < 0 \\ &\iff -\frac{2}{a} > \Delta t > 0 \quad (\text{since } a < 0) \end{aligned}$$

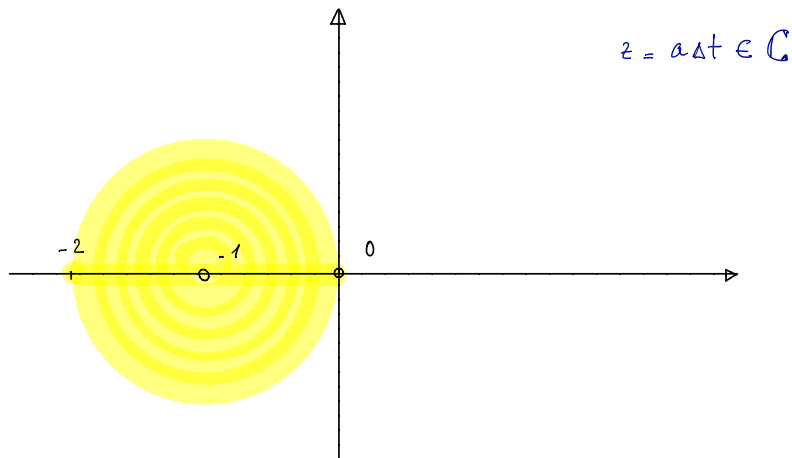
## Stability for Explicit Euler: the real setting



$$\begin{aligned} \text{EE is stable} &\iff |1 + a \Delta t| < 1 \\ &\iff -2 < \underbrace{a \Delta t}_z < 0 \end{aligned}$$



## Stability for Explicit Euler: the complex setting



$$\begin{aligned} EE \text{ is stable} &\iff |1 + \overbrace{a\Delta t}^z| < 1 \\ &\iff z \in \text{circle with radius 1 and center } -1 \end{aligned}$$

It holds:

$$|1 + a\Delta t| < 1 \iff |1 + a\Delta t|^2 < 1$$

but we have

$$|1 + a\Delta t|^2 = (1 + a\Delta t)(1 + \bar{a}\Delta t) = 1 + 2\operatorname{Re}(a)\Delta t + |a|^2\Delta t^2$$

Thus

$$|1 + a\Delta t| < 1 \iff 0 < \Delta t < -\frac{2\operatorname{Re}(a)}{|a|^2} =: \text{A-Stability condition for EE}$$

This is the drawback of Explicit Euler scheme, and of all the explicit schemes: for small enough time steps the stability condition is satisfied, but when  $\operatorname{Re}(a)$  is strongly negative (exactly the case of rapid decay in the true solution) we are compelled to keep  $\Delta t$  small.